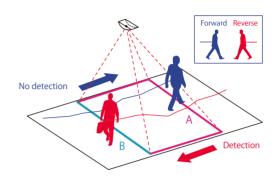
\$ ACCURANCE **R1002**

Reverse detection system



Reverse Detection System R1002 with an unique detection algorithm [Vector Focal Method] is designed to detect backward movement of human(s) in a specific area. The system are suitable for applications to catch a suspicious individual such as airports for an efficient facility management or security.



FEATURES

Accurate detection

An unique detection method [Vector Focal Method] grasps and tracks a shape of human sterically.

Reverse detection

Grasp all human movements and detect only backward movement

System corporation

Enable to be connected with an upper layer system by using no-voltage output from the control box.

SPECIFICATIONS Specifications Remarks Detection Method Vector Focusing Method Detection Accuracy > 95% (by own criteria) Power over Ethernet IEEE 802.3 af Supply Voltage Warm-up time Approx. 45 sec Control box 10 W max Power Consumption Detection unit 10 W max. Power (lit) Green Reverse detection (lit) Green / Red Warm-up (lit) / Trouble (blinking) Communication trouble (alternative blinking) Indicator Detection unit Green Power (lit) Red Reverse detection (lit) Warm-up (lit) / Trouble (blinking) Orange Communication trouble (alternative blinking) Green / Red Control box $265 \times 135 \times 31 \text{ mm}$ $(W \times H \times D)$ Dimensions 193 × 85 × 34 mm $(W \times H \times D)$ Detection unit Control box 800 g Weight Detection unit 220 g Operating Temperature 0 to 50°0 Operating Humidity only under < 80% RH only under no condensation no condensation Operating Illuminance only the 100 to 20,000 lux *1 only the outline of an object is shown outline of an object is show Control box Wall / stationary Interior only Install location Detection unit Ceiling Interior only Mounting Height Detection unit It may be limited by environmental conditions. CAT5e or large 100 m max. in length Protocol : TCP/UDP(IPv4), ARP, ICMP or HTTP 100Base-T(X) Ethernet Disable output Disable reverse detection [1] and [2] Input terminal *2 Output reset Stop the outputs of reverse detection [1] and [2] Reverse detection [1] Variable timer 0.2 to infinity Reverse detection [2] MOS FET relay Unit [1] detects Pulse output for reverse detection by unit [1] Pulse output for the number of reverse detection by unit [1] N.O./N.C. no voltage Output terminal *2 Unit [2] detects Pulse output for reverse detection by unit [2] Pulse output for the number of reverse detection by unit [2] 30 V DC 0.2 A or less Unit [3] detects Pulse output for reverse detection by unit [3] Pulse output for the number of reverse detection by unit [3] (Resistibility load) Number of reverse detections Pulse output for the number of reverse detection Output when disable to detect

^{*1} R1002 always requires 100 lux or more.
*2 Input/output relays can be selected N.O./N.C. by the dipswitch